

# Dyonic Taub-NUT Phases

## I - TN Thermodynamics :

### i) Background :

- \* Forms & Conservation laws
- \* Dirac Monopole

### ii) Taub-NUT space :

- \* Non-relativistic weak field limit
- \* Misner string

### iii) TN Thermodynamics :

- \* Unconstrained Thermodynamics
- \* Conserved charges of TN spaces
- \* Thermodynamics Ensembles and Regularity conditions
- \* Our approach to TN Thermodynamics

# Forms & Conservation Laws

\* A  $n$ -form is a fully anti-sym.  $n$ -rank tensor, or

Also written as  $w_{\mu_1, \dots, \mu_n}$

$$w = w_{\mu_1, \dots, \mu_n} dx^{\mu_1} \wedge dx^{\mu_2} \wedge \dots \wedge dx^{\mu_n}$$

\* Exterior derivative "d" which takes  $n$ -form  $\rightarrow$   $(n+1)$ -form,

$$dw = (n+1) \nabla_{[\mu_1} w_{\mu_2 \dots \mu_{n+1}]} dx^{\mu_1} \wedge \dots \wedge dx^{\mu_{n+1}}$$

\*  $ddw = 0$ , since  $\nabla_{[\mu} \nabla_{\nu]} w_{\mu_1 \dots \mu_n} = 0$ .

\* Hodge operation (\*) on an  $n$ -form  $\mapsto$   $(d-n)$ -form ( $d = \text{dim}$ )

$$(*w)_{\mu_{n+1} \dots d} = \frac{1}{n!} \epsilon^{\mu_1 \dots \mu_n}_{\mu_{n+1} \dots d} w_{\mu_1 \dots \mu_n}$$

Examples: EM vector pot.  $A_\mu(\varphi, \vec{A}) \equiv A$  (1-form)

$$dA = 2 \nabla_{[\mu} A_{\nu]} dx^\mu \wedge dx^\nu \rightarrow 2\text{-form.}$$

Maxwell's Eyn's  $\left\{ \begin{array}{l} \nabla_\mu F^{\nu\mu} = J^\nu \Rightarrow d(*F) = *J \\ \nabla_{[\mu} F_{\nu\alpha]} = 0 \Rightarrow dF = 0. \end{array} \right.$

## Stock's Theorem:

\* A conserved current  $\nabla_\mu J^\mu = 0 \iff d(*J) = 0$ .

$$(*J)_{\alpha\beta\gamma} = \epsilon^{\mu}_{\alpha\beta\gamma} J_\mu \Rightarrow (d*J)_{\alpha\beta\gamma\delta} \propto \epsilon_{\alpha\beta\gamma\delta} (\nabla_\mu J^\mu)$$

$$\therefore d(*J) = \epsilon_{\alpha\beta\gamma\delta} \nabla_\mu J^\mu dx^\alpha \wedge dx^\beta \wedge dx^\gamma \wedge dx^\delta$$

$$= \epsilon_{0123} \nabla_\mu J^\mu dx^0 \wedge dx^1 \wedge dx^2 \wedge dx^3$$

$$\int d(*J) = \int \sqrt{-g} \nabla_\mu J^\mu d^4x$$

Statement of Stokes's Theorem:

$$\int_{\mathcal{M}} d(*J) = \int_{\partial\mathcal{M}} *J$$

Similar to vector calculus Divergence's Theorem

$$\int_V \nabla \cdot \bar{A} dV = \oint_S \bar{A} \cdot d\bar{S}$$

Notice:

$$\partial\mathcal{M} = \Sigma_1 \cup \Sigma_2$$



$$\int_{\partial\mathcal{M}} *J = \int_{\Sigma_1} *J - \int_{\Sigma_2} *J \Rightarrow Q_1 = Q_2 \text{ (cons.)}$$

$$\therefore Q_e = \int_{\Sigma} *J = \int_{\Sigma} d*F = \int_{\partial\Sigma} *F$$

Also if  $dF = -*J_m \Rightarrow \int_{\Sigma} dF = \int_{\partial\Sigma} F = - \int_{\Sigma} *J_m = Q_m$

$$\therefore Q_m = - \int_{\partial\Sigma} F$$

$$Q_e = \int_{\partial\Sigma} *F$$

Notice:

if  $F \rightarrow *F$ ,  $*F \rightarrow **F = -F$ , one gets

$$\tilde{Q}_e = \int_{\partial\Sigma} **F = - \int_{\partial\Sigma} F = Q_m$$

$$\tilde{Q}_m = - \int_{\partial\Sigma} *F = -Q_e$$

$$\therefore Q_e \rightarrow Q_m \text{ \& } Q_m \rightarrow -Q_e \text{ (EM duality!)}$$

\* In GR we have a similar expression for obtaining total mass and angular momentum of a spacetime. These quantities are associated with spacetime isometry sym. which is connected to the existence of Killing vectors, or

$$\nabla^\mu \chi^\nu + \nabla^\nu \chi^\mu = 0.$$

\*  $\chi^{\mu(t)} = (1, 0, 0, 0)$  (time-translat. sym.)

\*  $\chi^{\mu(\varphi)} = (0, 0, 0, 1)$  (rotat. sym.)

$$Q_{(\chi)} = -c \int_{\partial \Sigma} (* d\chi) = \begin{cases} M \text{ (mass), for } \chi = \chi^{(t)} \\ J \text{ (Ang. mom. for } \chi = \chi^{(\varphi)} \end{cases}$$

\* Notice the similarity with electric charge  $Q$  and mass!

$$M = -c \int_{\partial \Sigma} (* d\chi^{(t)})$$

Do we have a dual quantforman? Yes it is the rot charge (parameter)

$$\tilde{M} = \int_{\partial \Sigma} (d\chi^{(t)}) = n. \quad (\text{in Minkowski space})$$

\* "n" is interpreted as a source for a magnetiz-type mass which is related to gravitomagnetiz phenomena!

To understand the nature of "n" and Tamb-NUT metric it is instructive to go over the topic of Dirac Monopole!

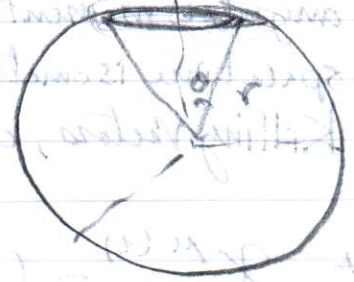
$$dl = \frac{a}{r \sin \theta} d\phi$$

$\approx a^2$

$$\oint_{S^2} \vec{B} \cdot d\vec{S} = \lim_{a \rightarrow 0} \int_{S^2} \vec{B} \cdot d\vec{S}$$

( $S^2$  - disk( $\omega$ ))

$$= \oint_{C_{-a}} \vec{A} \cdot d\vec{l} = \oint A_\phi a d\phi = 4\pi P$$



$$A_\phi \sim \frac{\# P}{a} \Rightarrow \frac{\# P}{r \sin \theta}$$

i.e.  $A_\phi$  is not well defined along z axis!

$$\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = M$$

$$M = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \tilde{M}$$

$M$  is invertible as a source for a magnetic field is related to vector potential through  $\vec{A} = \int \frac{\vec{j}(\vec{r}')}{|\vec{r} - \vec{r}'|} dV'$

To understand the nature of  $M$ , one has to understand its structure to go over the top of some things!

## Dirac Monopole:

Forcing the existence of magnetic monopole charge led Dirac to

$$\nabla \cdot \bar{\mathbf{B}} = 4\pi\rho \quad \bar{\mathbf{B}} = \frac{P}{r^2} \hat{\mathbf{e}}_r.$$

$$\oint \bar{\mathbf{B}} \cdot d\bar{\mathbf{A}} = 4\pi\rho \quad \bar{\mathbf{B}} \stackrel{?}{=} \nabla \times \bar{\mathbf{A}}.$$

\* In fact we can write  $\bar{\mathbf{B}} = \nabla \times \bar{\mathbf{A}}$ , but  $\bar{\mathbf{A}}$  can not be well defined globally, or

$$A^\varphi = \frac{P}{r \sin\theta} (\cos\theta + C).$$

\* Notice that, when  $C=0$ ,  $A^\varphi$  is not well defined along z-axis.

\* But one can have a well-defined  $A$  using two patches?

$$A^\varphi = \begin{cases} A_{(N)}^\varphi = \frac{P}{r \sin\theta} (\cos\theta - 1), & z > 0. \\ A_{(S)}^\varphi = \frac{P}{r \sin\theta} (\cos\theta + 1), & z < 0. \end{cases}$$

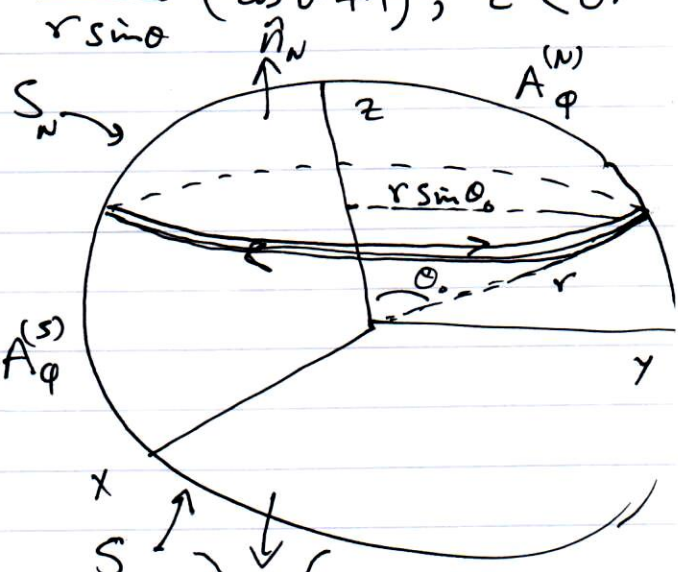
$$P = \frac{1}{4\pi} \oint \bar{\mathbf{B}} \cdot d\bar{\mathbf{S}}$$

$$= \frac{1}{4\pi} \left[ \int_{S_N} \bar{\mathbf{B}} \cdot d\bar{\mathbf{S}} + \int_{S_S} \bar{\mathbf{B}} \cdot d\bar{\mathbf{S}} \right]$$

$$= \frac{1}{4\pi} \left[ \oint_{C_N} \bar{\mathbf{A}} \cdot d\bar{\mathbf{r}} + \oint_{C_S} \bar{\mathbf{A}} \cdot d\bar{\mathbf{r}} \right]$$

$$= \frac{r_0 \sin\theta_0}{4\pi} \left[ \int_{C_N} A_{(N)}^\varphi d\varphi - \int_{C_S} A_{(S)}^\varphi d\varphi \right] = P.$$

$$= \frac{r \sin\theta_0}{4\pi} \left[ \frac{P}{r \sin\theta_0} (\cos\theta_0 + 1) - \hat{\mathbf{n}}_S \cdot \left( \frac{P}{r \sin\theta_0} (\cos\theta_0 - 1) \right) \right] (2\pi)$$



Tamb-NUT metric in Minkowski space:

$$* dS^2 = -f (dt + 2n \cos\theta d\varphi)^2 + f^{-1} dr^2 + (r^2 + n^2) (d\theta^2 + \sin^2\theta d\varphi^2)$$

$$f = \frac{r^2 - n^2 - 2Mr}{r^2 + n^2}, \quad M \text{ is mass parameter, } n \text{ is nut parameter.}$$

\* Notice:

- Metric goes to Schw. as  $n \rightarrow 0$ .
- Metric does not go to Minkowski as  $m \rightarrow 0$ !

\* To understand this metric one better go to Newtonian limit  
In this limit  $g_{\mu\nu} \approx \eta_{\mu\nu} + h_{\mu\nu}$  (small) for big mass  $M$ .

$$\frac{dx^i}{dt} \ll 1, \text{ for test mass } m!$$

\* For the large mass  $M$ , one gets

$$\text{the } G_{\mu\nu} = K T_{\mu\nu} \Rightarrow \nabla^2 \phi = 0$$

for small mass

$$\frac{d^2 x^i}{dt^2} + \Gamma_{\alpha\beta}^i \frac{dx^\alpha}{dt} \frac{dx^\beta}{dt} = 0 \Rightarrow m \frac{d^2 x^i}{dt^2} = m \partial_i \phi \quad t = \tau$$

$$\Rightarrow \phi = -\frac{M}{r} \Rightarrow S_p \sim \int dt \left( \frac{1}{2} m v^2 - m \phi \right).$$

\* Perturbations can be decomposed

$$g_{\mu\nu} = \eta_{\mu\nu} + h_{\mu\nu} \quad h_{\mu\nu} =$$

$$\begin{cases} h_{00} \rightarrow \text{scalar (1)} \\ h_{0i} \rightarrow \text{vector (3)} \\ h_{ij} \rightarrow \text{tensor (6)} \end{cases}$$

\* GR predicts the possibility of deviating from Newtonian gravity in weak field limit / non-relativistic limit if  $h_{0i} = A_i$  is non-vanishing asympt. as  $r \rightarrow \infty$ . This is what happens in Tamb-NUT space

$$ASr \rightarrow \infty \quad dS^2 = -dt^2 + r^2 d\Omega^2 - 4n \cos\theta dt d\varphi.$$

$$h_{0i} = A_\varphi = -2n \cos\theta.$$

Doing the weak field + non-relativistic limit

$$h_{00} = -2\phi_a, \quad \phi = -\frac{M}{r} \quad h_{0i} = A_i, \quad A_\phi = -2nc\cos\theta.$$

In this case the E.O.M of a test particle with mass "m" is

$$\text{with } m \frac{d^2 x^i}{dt^2} = -m \partial_i \phi_a + \frac{m}{c} [\vec{v} \times (\nabla \times \vec{A}_a)]_i$$

$$\vec{a} = -\frac{M}{r^2} \hat{\sigma} - \frac{2nc}{r^2} (v_\phi \hat{\sigma} - v_\theta \hat{\phi})$$

$$|\vec{a}| = \sqrt{M^2 + 4n^2 c^2 (v_\theta^2 + v_\phi^2)} / r^2.$$

with Lagrangian

$$S_p \sim \int dt \left( \frac{1}{2} m v^2 - m \phi_a + \frac{m}{c} \vec{A}_a \cdot \vec{v} \right)$$

which is similar to a particle under the influence of Lorentz force

$$S_p \sim \int dt \left( \frac{1}{2} m v^2 - e \phi_e + \frac{e}{c} \vec{A}_e \cdot \vec{v} \right).$$

$A_i$  is the source of gravitomagnetic field, with the charge "n"

$$n = \int \frac{d^4 x^{(t)}}{\partial \Sigma^0} \quad (\text{dual mass!})$$

\* Therefore, TN is interpreted as a gravitational charge!

\* Also, n is automatically conserved!